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Glocalized Solutions for Sustainability in Manufacturing - Jürgen Hesselbach 2011-03-19
The 18th CIRP International Conference on Life Cycle Engineering (LCE) 2011 continues a long tradition of scientific meetings focusing on the exchange of industrial

and academic knowledge and experiences in life cycle assessment, product development, sustainable manufacturing and end-of-life-management. The theme "Glocalized Solutions for Sustainability in Manufacturing" addresses the need for engineers

to develop solutions which have the potential to address global challenges by providing products, services and processes taking into account local capabilities and constraints to achieve an economically, socially and environmentally sustainable society in a global perspective. Glocalized Solutions for Sustainability in Manufacturing do not only involve products or services that are changed for a local market by simple substitution or the omitting of functions. Products and services need to be addressed that ensure a high standard of living everywhere. Resources required for manufacturing and use of such products are limited and not evenly distributed in the world. Locally available

resources, local capabilities as well as local constraints have to be drivers for product- and process innovations with respect to the entire life cycle. The 18th CIRP International Conference on Life Cycle Engineering (LCE) 2011 serves as a platform for the discussion of the resulting challenges and the collaborative development of new scientific ideas. **Solutions Manual, Modern Control Engineering, Fourth Edition** - Katsuhiko Ogata 2002

Proceedings of the 3rd International Conference on Intelligent Technologies and Engineering Systems (ICITES2014) - Jengnan Juang 2015-11-12
This book includes the original, peer reviewed research from the 3rd International Conference on Intelligent

Technologies and Engineering Systems (ICITES2014), held in December, 2014 at Cheng Shiu University in Kaohsiung, Taiwan. Topics covered include: Automation and robotics, fiber optics and laser technologies, network and communication systems, micro and nano technologies and solar and power systems. This book also Explores emerging technologies and their application in a broad range of engineering disciplines Examines fiber optics and laser technologies Covers biomedical, electrical, industrial and mechanical systems Discusses multimedia systems and applications, computer vision and image & video signal processing
Modern Control Systems - Richard C. Dorf 1980

Robust Control Engineering - Mario

Garcia-Sanz 2017-06-26
This book thoroughly covers the fundamentals of the QFT robust control, as well as practical control solutions, for unstable, time-delay, non-minimum phase or distributed parameter systems, plants with large model uncertainty, high-performance specifications, nonlinear components, multi-input multi-output characteristics or asymmetric topologies. The reader will discover practical applications through a collection of fifty successful, real world case studies and projects, in which the author has been involved during the last twenty-five years, including commercial wind turbines, wastewater treatment plants, power systems, satellites with flexible appendages, spacecraft, large radio telescopes, and

industrial manufacturing systems. Furthermore, the book presents problems and projects with the popular QFT Control Toolbox (QFTCT) for MATLAB, which was developed by the author. Real-time Iterative Learning Control - Jian-Xin Xu 2008-12-12 Real-time Iterative Learning Control demonstrates how the latest advances in iterative learning control (ILC) can be applied to a number of plants widely encountered in practice. The book gives a systematic introduction to real-time ILC design and source of illustrative case studies for ILC problem solving; the fundamental concepts, schematics, configurations and generic guidelines for ILC design and implementation are enhanced by a well-selected group of

representative, simple and easy-to-learn example applications. Key issues in ILC design and implementation in linear and nonlinear plants pervading mechatronics and batch processes are addressed, in particular: ILC design in the continuous- and discrete-time domains; design in the frequency and time domains; design with problem-specific performance objectives including robustness and optimality; design in a modular approach by integration with other control techniques; and design by means of classical tools based on Bode plots and state space.

Modelling and Control of Robot Manipulators - Lorenzo Sciavicco 2012-12-06 Fundamental and technological topics are blended uniquely and developed clearly in

nine chapters with a gradually increasing level of complexity. A wide variety of relevant problems is raised throughout, and the proper tools to find engineering-oriented solutions are introduced and explained, step by step. Fundamental coverage includes: Kinematics; Statics and dynamics of manipulators; Trajectory planning and motion control in free space. Technological aspects include: Actuators; Sensors; Hardware/software control architectures; Industrial robot-control algorithms. Furthermore, established research results involving description of end-effector orientation, closed kinematic chains, kinematic redundancy and singularities, dynamic parameter identification, robust and adaptive control and

force/motion control are provided. To provide readers with a homogeneous background, three appendices are included on: Linear algebra; Rigid-body mechanics; Feedback control. To acquire practical skill, more than 50 examples and case studies are carefully worked out and interwoven through the text, with frequent resort to simulation. In addition, more than 80 end-of-chapter exercises are proposed, and the book is accompanied by a solutions manual containing the MATLAB code for computer problems; this is available from the publisher free of charge to those adopting this work as a textbook for courses.

Designing Linear Control Systems with MATLAB -

Katsuhiko Ogata 1994

Written as a companion volume to the author's

Solving Control Engineering Problems with MATLAB, this indispensable guide illustrates the power of MATLAB as a tool for synthesizing control systems, emphasizing pole placement, and optimal systems design. **Modern Control Theory** - William L. Brogan 1991

Control Systems Engineering - Norman S. Nise 1995-01-15

Modern Control Systems - Richard C. Dorf 2011 Modern Control Systems, 12e, is ideal for an introductory undergraduate course in control systems for engineering students. Written to be equally useful for all engineering disciplines, this text is organized around the concept of control systems theory as it has been developed in the frequency and time domains. It

provides coverage of classical control, employing root locus design, frequency and response design using Bode and Nyquist plots. It also covers modern control methods based on state variable models including pole placement design techniques with full-state feedback controllers and full-state observers. Many examples throughout give students ample opportunity to apply the theory to the design and analysis of control systems. Incorporates computer-aided design and analysis using MATLAB and LabVIEW MathScript.

Power Electronic Systems - Anish Deb 2017-12-19 A Totally Different Outlook on Power Electronic System Analysis Power Electronic Systems: Walsh Analysis with MATLAB® builds a case for Walsh analysis as a

powerful tool in the study of power electronic systems. It considers the application of Walsh functions in analyzing power electronic systems, and the advantages offered by Walsh domain analysis of power electronic systems. Solves Power Electronic Systems in an Unconventional Way This book successfully integrates power electronics as well as systems and control. Incorporating a complete orthonormal function set very much unlike the sine-cosine functions, it introduces a blending between piecewise constant orthogonal functions and power electronic systems. It explores the background and evolution of power electronics, and discusses Walsh and related orthogonal basis functions. It develops the mathematical

foundation of Walsh analysis, and first- and second-order system analyses by Walsh technique. It also describes the Walsh domain operational method and how it is applied to linear system analysis. Introduces Theories Step by Step While presenting the underlying principles of Walsh analysis, the authors incorporate many illustrative examples, and include a basic introduction to linear algebra and MATLAB® programs. They also examine different orthogonal piecewise constant basis functions like Haar, Walsh, slant, block pulse functions, and other related orthogonal functions along with their time scale evolution. • Analyzes pulse-fed single input single output (SISO) first- and second-order systems • Considers stepwise and

continuously pulse width modulated chopper systems • Describes a detailed analysis of controlled rectifier circuits • Addresses inverter circuits Power Electronic Systems: Walsh Analysis with MATLAB® is written for postgraduate students, researchers, and academicians in the area of power electronics as well as systems and control.

Engineering System

Dynamics - Forbes T.

Brown 2006-08-15

For today's students, learning to model the dynamics of complex systems is increasingly important across nearly all engineering disciplines. First published in 2001, Forbes T. Brown's Engineering System Dynamics: A Unified Graph-Centered Approach introduced students to a unique and highly successful approach to

modeling system dynamics using bond graphs.

Updated with nearly one-third new material, this second edition expands this approach to an even broader range of topics. What's New in the Second Edition? In addition to new material, this edition was restructured to build students' competence in traditional linear mathematical methods before they have gone too far into the modeling that still plays a pivotal role. New topics include magnetic circuits and motors including simulation with magnetic hysteresis; extensive new material on the modeling, analysis, and simulation of distributed-parameter systems; kinetic energy in thermodynamic systems; and Lagrangian and Hamiltonian methods. MATLAB® figures prominently in this

edition as well, with code available for download from the Internet. This code includes simulations for problems that appear in the later chapters as well as code for selected thermodynamic substances. Using a step-by-step pedagogy accompanied by abundant examples, graphs, illustrations, case studies, guided exercises, and homework problems, *Engineering System Dynamics: A Unified Graph-Centered Approach, Second Edition* is a text that students will embrace and continue to use well into their careers. While the first half of the book is ideal for junior-level undergraduates, the entire contents are suited for more advanced students.

Triangular Orthogonal Functions for the Analysis of Continuous

Time Systems - Anish Deb
2011-05-15

This book deals with a new set of triangular orthogonal functions, which evolved from the set of well-known block pulse functions (BPF), a major member of the piecewise constant orthogonal function (PCOF) family. Unlike PCOF, providing staircase solutions, this new set of triangular functions provides piecewise linear solution with less mean integral squared error (MISE). After introducing the rich background of PCOF family, which includes Walsh, block pulse and other related functions, fundamentals of the newly proposed set – such as basic properties, function approximation, integral operational metrics, etc. – are presented. This set has been used for integration of

functions, analysis and synthesis of dynamic systems and solution of integral equations. The study ends with microprocessor based simulation of SISO control systems using sample-and-hold functions and Dirac delta functions.

Control Systems–GATE, PSUS AND ES Examination

- Satish K Karna

Test Prep for Control Systems–GATE, PSUS AND ES Examination

Analysis and Identification of Time-Invariant Systems, Time-Varying Systems, and Multi-Delay Systems using Orthogonal Hybrid Functions - Anish Deb

2016-01-05

This book introduces a new set of orthogonal hybrid functions (HF) which approximates time functions in a piecewise linear manner which is very suitable for practical applications. The book presents an

analysis of different systems namely, time-invariant system, time-varying system, multi-delay systems---both homogeneous and non-homogeneous type- and the solutions are obtained in the form of discrete samples. The book also investigates system identification problems for many of the above systems. The book is spread over 15 chapters and contains 180 black and white figures, 18 colour figures, 85 tables and 56 illustrative examples. MATLAB codes for many such examples are included at the end of the book.

Integrated Frequency Synthesis for Convergent Wireless Solutions - Jad G. Atallah

2012-05-30

This book describes the design and implementation of an electronic subsystem called the frequency synthesizer, which is a

very important building block for any wireless transceiver. The discussion includes several new techniques for the design of such a subsystem which include the usage modes of the wireless device, including its support for several leading-edge wireless standards. This new perspective for designing such a demanding subsystem is based on the fact that optimizing the performance of a complete system is not always achieved by optimizing the performance of its building blocks separately. This book provides “hands-on” examples of this sort of co-design of optimized subsystems, which can make the vision of an always-best-connected scenario a reality.

Solutions Manual, Modern Control Engineering - Katsuhiko Ogata 1990

Linear Control System Analysis and Design with MATLAB®, Sixth Edition - Constantine H. Houptis 2013-10-30

Thoroughly classroom-tested and proven to be a valuable self-study companion, *Linear Control System Analysis and Design: Sixth Edition* provides an intensive overview of modern control theory and conventional control system design using in-depth explanations, diagrams, calculations, and tables. Keeping mathematics to a minimum, the book is designed with the undergraduate in mind, first building a foundation, then bridging the gap between control theory and its real-world application. Computer-aided design accuracy checks (CADAC) are used throughout the text to enhance computer literacy. Each CADAC uses fundamental

concepts to ensure the viability of a computer solution. Completely updated and packed with student-friendly features, the sixth edition presents a range of updated examples using MATLAB®, as well as an appendix listing MATLAB functions for optimizing control system analysis and design. Over 75 percent of the problems presented in the previous edition have been revised or replaced.

Handbook of Control Systems Engineering -
Louis C. Westphal
2012-12-06

This book is a revision and extension of my 1995 Sourcebook of Control Systems Engineering. Because of the extensions and other modifications, it has been retitled Handbook of Control Systems Engineering, which it is intended to be for its

prime audience: advanced undergraduate students, beginning graduate students, and practising engineers needing an understandable review of the field or recent developments which may prove useful. There are several differences between this edition and the first. • Two new chapters on aspects of nonlinear systems have been incorporated. In the first of these, selected material for nonlinear systems is concentrated on four aspects: showing the value of certain linear controllers, arguing the suitability of algebraic linearization, reviewing the semi-classical methods of harmonic balance, and introducing the nonlinear change of variable technique known as feedback linearization. In the second chapter, the topic of variable structure control, often

with sliding mode, is introduced. • Another new chapter introduces discrete event systems, including several approaches to their analysis. • The chapters on robust control and intelligent control have been extensively revised. • Modest revisions and extensions have also been made to other chapters, often to incorporate extensions to nonlinear systems.

Modern Control System Theory - M. Gopal 1993

About the book... The book provides an integrated treatment of continuous-time and discrete-time systems for two courses at postgraduate level, or one course at undergraduate and one course at postgraduate level. It covers mainly two areas of modern control theory, namely; system theory, and multivariable and optimal control. The

coverage of the former is quite exhaustive while that of latter is adequate with significant provision of the necessary topics that enables a research student to comprehend various technical papers. The stress is on interdisciplinary nature of the subject.

Practical control problems from various engineering disciplines have been drawn to illustrate the potential concepts. Most of the theoretical results have been presented in a manner suitable for digital computer programming along with the necessary algorithms for numerical computations.

Feedback Systems - Karl Johan Åström 2021-02-02

The essential introduction to the principles and applications of feedback systems—now fully revised and expanded

This textbook covers the mathematics needed to model, analyze, and design feedback systems. Now more user-friendly than ever, this revised and expanded edition of Feedback Systems is a one-volume resource for students and researchers in mathematics and engineering. It has applications across a range of disciplines that utilize feedback in physical, biological, information, and economic systems. Karl Åström and Richard Murray use techniques from physics, computer science, and operations research to introduce control-oriented modeling. They begin with state space tools for analysis and design, including stability of solutions, Lyapunov functions, reachability, state feedback observability, and estimators. The matrix exponential plays a

central role in the analysis of linear control systems, allowing a concise development of many of the key concepts for this class of models. Åström and Murray then develop and explain tools in the frequency domain, including transfer functions, Nyquist analysis, PID control, frequency domain design, and robustness. Features a new chapter on design principles and tools, illustrating the types of problems that can be solved using feedback Includes a new chapter on fundamental limits and new material on the Routh-Hurwitz criterion and root locus plots Provides exercises at the end of every chapter Comes with an electronic solutions manual An ideal textbook for undergraduate and graduate students Indispensable for

researchers seeking a self-contained resource on control theory

Steel Design - William T. Segui 2012-08-01

STEEL DESIGN covers the fundamentals of structural steel design with an emphasis on the design of members and their connections, rather than the integrated design of buildings. The book is designed so that instructors can easily teach LRFD, ASD, or both, time-permitting. The application of fundamental principles is encouraged for design procedures as well as for practical design, but a theoretical approach is also provided to enhance student development. While the book is intended for junior-and senior-level engineering students, some of the later chapters can be used in graduate courses and practicing engineers

will find this text to be an essential reference tool for reviewing current practices. Important Notice: Media content referenced within the product description or the product text may not be available in the ebook version.

Control Applications of Vehicle Dynamics - Jingsheng Yu 2021-12-20

This book presents essential knowledge of car vehicle dynamics and control theory with NI LabVIEW software product application, resulting in a practical yet highly technical guide for designing advanced vehicle dynamics and vehicle system controllers. Presenting a clear overview of fundamental vehicle dynamics and vehicle system mathematical models, the book covers linear and non-linear design of model based controls such as wheel

slip control, vehicle speed control, path following control, vehicle stability and rollover control, stabilization of vehicle-trailer system. Specific applications to autonomous vehicles are described among the methods. It details the practical applications of Kalman-Bucy filtering and the observer design for sensor signal estimation, alongside lateral vehicle dynamics and vehicle rollover dynamics. The book also discusses high level controllers, alongside a clear explanation of basic control principles for regenerative braking in both electric and hybrid vehicles, and wheel torque vectoring systems. Concrete LabVIEW simulation examples of how the models and controls are used in representative applications, along with software algorithms and

LabVIEW block diagrams are illustrated. It will be of interest to engineering students, automotive engineering students and automotive engineers and researchers.

Modern Control Engineering - P.N. Paraskevopoulos
2017-12-19

"Illustrates the analysis, behavior, and design of linear control systems using classical, modern, and advanced control techniques. Covers recent methods in system identification and optimal, digital, adaptive, robust, and fuzzy control, as well as stability, controllability, observability, pole placement, state observers, input-output decoupling, and model matching."

Optimization and Control with Applications -
Liqun Qi 2006-03-30
A collection of 28

refereed papers grouped according to four broad topics: duality and optimality conditions, optimization algorithms, optimal control, and variational inequality and equilibrium problems. Suitable for researchers, practitioners and postgrads.

Modern Control System Theory and Design -

Stanley M. Shinnars
1992-03-25

Offers unified treatment of conventional and modern continuous and discrete control theory and demonstrates how to apply the theory to realistic control system design problems. Along with linear and nonlinear, digital and optimal control systems, it presents four case studies of actual designs. The majority of solutions contained in the book and the problems at the ends of the chapters were

generated using the commercial software package, MATLAB, and is available free to the users of the book by returning a postcard contained with the book to the MathWorks, Inc. This software also contains the following features/utilities created to enhance MATLAB and several of the MathWorks' toolboxes: Tutorial File which contains the essentials necessary to understand the MATLAB interface (other books require additional books for full comprehension), Demonstration m-file which gives the users a feel for the various utilities included, OnLine HELP, Synopsis File which reviews and highlights the features of each chapter.

Discrete-time Control Systems - Katsuhiko Ogata 1995

A comprehensive treatment of the

analysis and design of discrete-time control systems which provides a gradual development of the theory by emphasizing basic concepts and avoiding highly mathematical arguments. The text features comprehensive treatment of pole placement, state observer design, and quadratic optimal control.

Modern Control of DC-Based Power Systems - Marco Cupelli 2018-06-08
Modern Control of DC-Based Power Systems: A Problem-Based Approach addresses the future challenges of DC Grids in a problem-based context for practicing power engineers who are challenged with integrating DC grids in their existing architecture. This reference uses control theory to address the main concerns affecting these systems, things

like generation capacity, limited maximum load demands and low installed inertia which are all set to increase as we move towards a full renewable model. Offering a new approach for a problem-based, practical approach, the book provides a coordinated view of the topic with MATLAB®, Simulink® files and additional ancillary material provided.

Includes Simulink® Files (of examples and for lab training classes) and MATLAB® files Presents video slides to support the problem-based approach to understanding DC Power System control and application Provides stability analysis of DC networks and examples of common stability problems

Process Control Design for Industrial Applications - Dumitru Popescu 2017-04-12

This book presents the most important methods used for the design of digital controls implemented in industrial applications. The best modelling and identification techniques for dynamical systems are presented as well as the algorithms for the implementation of the modern solutions of process control. The proposed described methods are illustrated by various case studies for the main industrial sectors There exist a number of books related each one to a single type of control, yet usually without comparisons for various industrial sectors. Some other books present modelling and identification methods or signal processing. This book presents the methods to solve all the problems linked to the design of a process control without the need

to find additional information.

Modern Control System Theory - M. Gopal
1993-10-19

An updated and refined edition of the original presenting both continuous-time and discrete-time systems. Emphasizes the use of PCs to solve complex control system problems easily and efficiently. Provides a computer-aided learning environment with any commercially available CAD software. Features practical illustrations from various branches of engineering, numerous worked examples and exercises.

Applied Electromechanical Devices and Machines for Electric Mobility Solutions - Adel El-Shahat 2020-03-25

In this book, highly qualified multidisciplinary scientists present their

recent research that has been motivated by the significance of applied electromechanical devices and machines for electric mobility solutions. It addresses advanced applications and innovative case studies for electromechanical parameter identification, modeling, and testing of; permanent-magnet synchronous machine drives; investigation on internal short circuit identifications; induction machine simulation; CMOS active inductor applications; low-cost wide-speed operation generators; hybrid electric vehicle fuel consumption; control technologies for high-efficient applications; mechanical and electrical design calculations; torque control of a DC motor with a state-space estimation; and 2D-

layered nanomaterials for energy harvesting. This book is essential reading for students, researchers, and professionals interested in applied electromechanical devices and machines for electric mobility solutions.

Control Systems -

Jitendra R. Raol

2019-07-12

Control Systems:

Classical, Modern, and

AI-Based Approaches

provides a broad and

comprehensive study of

the principles,

mathematics, and

applications for those

studying basic control

in mechanical,

electrical, aerospace,

and other engineering

disciplines. The text

builds a strong

mathematical foundation

of control theory of

linear, nonlinear,

optimal, model

predictive, robust,

digital, and adaptive

control systems, and it addresses applications in several emerging areas, such as aircraft, electro-mechanical, and some nonengineering systems: DC motor control, steel beam thickness control, drum boiler, motion control system, chemical reactor, head-disk assembly, pitch control of an aircraft, yaw-damper control, helicopter control, and tidal power control. Decentralized control, game-theoretic control, and control of hybrid systems are discussed. Also, control systems based on artificial neural networks, fuzzy logic, and genetic algorithms, termed as AI-based systems are studied and analyzed with applications such as auto-landing aircraft, industrial process control, active suspension system, fuzzy gain scheduling, PID

control, and adaptive neuro control. Numerical coverage with MATLAB® is integrated, and numerous examples and exercises are included for each chapter. Associated MATLAB® code will be made available.

Modern Control Engineering - Maxwell Noton 2014-06-20

Modern Control Engineering focuses on the methodologies, principles, approaches, and technologies employed in modern control engineering, including dynamic programming, boundary iterations, and linear state equations. The publication first ponders on state representation of dynamical systems and finite dimensional optimization. Discussions focus on optimal control of dynamical discrete-time systems, parameterization of dynamical control

problems, conjugate direction methods, convexity and sufficiency, linear state equations, transition matrix, and stability of discrete-time linear systems. The text then tackles infinite dimensional optimization, including computations with inequality constraints, gradient method in function space, quasilinearization, computation of optimal control-direct and indirect methods, and boundary iterations. The book takes a look at dynamic programming and introductory stochastic estimation and control. Topics include deterministic multivariable observers, stochastic feedback control, stochastic linear-quadratic control problem, general calculation of optimal control by dynamic programming, and results

for linear multivariable digital control systems. The publication is a dependable reference material for engineers and researchers wanting to explore modern control engineering.

Modern Control Engineering - Katsuhiko Ogata 1997

"Comprehensive treatment of the analysis and design of continuous-time control systems"

Partial contents : The Laplace transform ; Mathematical modelling of dynamic system ; Transient-response analysis ; Root-locus analysis ; Frequency response analysis ; PID controls and introduction to robust control ; Control systems in state space ; Liapunov stability analysis and quadratic optimal control.

System Dynamics - Katsuhiko Ogata 2013-07-24

For junior-level courses

in System Dynamics, offered in Mechanical Engineering and Aerospace Engineering departments. This text presents students with the basic theory and practice of system dynamics. It introduces the modeling of dynamic systems and response analysis of these systems, with an introduction to the analysis and design of control systems.

Modern Control Systems - Richard C. Dorf 2017
For courses in Control Theory Developing Problem-Solving Skills Through Integrated Design and Analysis The purpose of Dorf's Modern Control Systems, Thirteenth Edition is to present the structure of feedback control theory and to provide a sequence of exciting discoveries. The book demonstrates various real-world, global engineering problems

while touching on evolving design strategies like green technology. Some of the themes at-hand include climate change, clean water, sustainability, waste management, emissions reduction, and minimizing energy. Throughout the text, students apply theory to the design and analysis of control systems. The Thirteenth Edition continues to explore the role of and need for automated and precise control systems in green engineering. Key examples of green engineering, such as wind turbine control and the modeling of a photovoltaic generator to achieve maximum power delivery, are discussed in detail. The text is organized around the concept of control systems theory in the context of frequency and time domains. Written to be equally useful for

all engineering disciplines, it covers topics such as classical control, employing root locus design, frequency and response design using Bode and Nyquist plots.

Modern Control Engineering - Katsuhiko Ogata 1970

This comprehensive treatment of the analysis and design of continuous-time control systems provides a "gradual" development of control theory and shows how to solve "all" computational problems with MATLAB. It avoids highly mathematical arguments, and features an abundance of examples and worked problems throughout the book. Chapter topics include the Laplace transform; mathematical modeling of mechanical systems, electrical systems, fluid systems, and thermal systems; transient and steady-

state-response analyses, root-locus analysis and control systems design by the root-locus method; frequency-response analysis and control systems design by the frequency-response; two-degrees-of-freedom control; state space analysis of control systems and design of control systems in state space. For control systems engineers.

Introduction to Process Control - Jose A. Romagnoli 2016-04-19

Introduction to Process Control, Second Edition provides a bridge between the traditional view of process control and the current, expanded role by blending conventional topics with a broader perspective of more integrated process operation, control, and information systems. Updating and expanding the content of its

predecessor, this second edition

Fractional-Order Models for Nuclear Reactor

Analysis - Gilberto Espinosa Paredes

2020-10-22

Fractional-Order Models for Nuclear Reactor Analysis presents fractional modeling issues in the context of anomalous diffusion processes in an accessible and practical way. The book emphasizes the importance of non-Fickian diffusion in heterogeneous systems as the core of the nuclear reactor, as well as different variations of diffusion processes in nuclear reactors which are presented to establish the importance of nuclear and thermohydraulic phenomena and the physical side effects of feedback. In addition, the book analyzes core issues in fractional modeling in nuclear

reactors surrounding phenomenological description and important analytical sub-diffusive processes in the transport neutron. Users will find the most innovative modeling techniques of nuclear reactors using operator differentials of fractional order and applications in nuclear design and reactor dynamics. Proposed methods are tested with Boltzmann equations and non-linear order models alongside real data from nuclear power plants, making this a valuable resource for nuclear professionals, researchers and graduate students, as well as those working in nuclear research centers with expertise in mathematical modeling, physics and control. Presents and analyzes a new paradigm of nuclear reactor phenomena with fractional modeling

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Considers principles of fractional calculation, methods of solving differential equations of fractional order, and their applications

Includes methodologies of linear and nonlinear analysis, along with design and dynamic analyses